

MATH 2205 - Calculus II Lecture Notes 17

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1 Integration Techniques

1.1 Basic Approaches

Proposition 1.1 (Basic Integration Formulas).

- (a) $\int k \, dx = kx + C, k \in \mathbb{R} \text{ (} k \text{ is real)}.$
- (b) $\int x^p \, dx = \frac{x^{p+1}}{p+1} + C, p \neq -1 \in \mathbb{R}.$
- (c) $\int \cos ax \, dx = \frac{1}{a} \sin ax + C.$
- (d) $\int \sin ax \, dx = -\frac{1}{a} \cos ax + C.$
- (e) $\int \sec^2 ax \, dx = \frac{1}{a} \tan ax + C.$
- (f) $\int \csc^2 ax \, dx = -\frac{1}{a} \cot ax + C.$
- (g) $\int \sec ax \tan ax \, dx = \frac{1}{a} \sec ax + C.$
- (h) $\int \csc ax \cot ax \, dx = -\frac{1}{a} \csc ax + C.$
- (i) $\int e^{ax} \, dx = \frac{1}{a} e^{ax} + C.$
- (j) $\int \frac{1}{x} \, dx = \ln |x| + C.$
- (k) $\int \frac{1}{\sqrt{a^2 - x^2}} \, dx = \sin^{-1} \frac{x}{a} + C.$
- (l) $\int \frac{1}{a^2 + x^2} \, dx = \frac{1}{a} \tan^{-1} \frac{x}{a} + C.$
- (m) $\int \frac{1}{x\sqrt{x^2 - a^2}} \, dx = \frac{1}{a} \sec^{-1} \left| \frac{x}{a} \right| + C, a > 0.$

1.2 Integration by Parts

Theorem 1.1 (Integration by Parts). Suppose that u and v are differentiable functions. Then

$$\int u \, dv = uv - \int v \, du.$$

Theorem 1.2 (Integration by Parts for Definite Integrals). Let u and v be differentiable. Then

$$\int_a^b u(x)v'(x) \, dx = u(x)v(x) \Big|_a^b - \int_a^b v(x)u'(x) \, dx.$$

1.3 Trigonometric Integrals

1.3.1 Integrating Powers of $\sin x$ or $\cos x$

Procedure 1.1. Strategies for evaluating integrals of the form $\int \sin^m x \, dx$ or $\int \cos^n x \, dx$, where m and n are positive integers, using trigonometric identities.

- (a) Integrals involving odd powers of $\cos x$ (or $\sin x$) are most easily evaluated by splitting off a single factor of $\cos x$ (or $\sin x$). For example, rewrite $\cos^5 x$ as $\cos^4 x \cdot \cos x$.
- (b) With even positive powers of $\sin x$ or $\cos x$, we use the half-angle formulas

$$\sin^2 \theta = \frac{1 - \cos 2\theta}{2} \text{ and } \cos^2 \theta = \frac{1 + \cos 2\theta}{2},$$

to reduce the powers in the integrand.

1.3.2 Integrating Products of Powers of $\sin x$ and $\cos x$

Procedure 1.2. Strategies for evaluating integrals of the form $\int \sin^m x \cos^n x \, dx$.

- (a) When m is odd and positive, n real. Split off $\sin x$, rewrite the resulting even power of $\sin x$ in terms of $\cos x$, and then use $u = \cos x$.
- (b) When n is odd and positive, m real. Split off $\cos x$, rewrite the resulting even power of $\cos x$ in terms of $\sin x$, and then use $u = \sin x$.
- (c) When m, n are both even and nonnegative. Use half-angle formulas to transform the integrand into polynomial in $\cos 2x$ and apply the preceding strategies once again to powers of $\cos 2x$ greater than 1.

Proposition 1.2 (Reduction Formulas). Assume n is a positive integer.

- (a) $\int \sin^n x \, dx = -\frac{\sin^{n-1} x \cos x}{n} + \frac{n-1}{n} \int \sin^{n-2} x \, dx.$
- (b) $\int \cos^n x \, dx = \frac{\cos^{n-1} x \sin x}{n} + \frac{n-1}{n} \int \cos^{n-2} x \, dx.$
- (c) $\int \tan^n x \, dx = \frac{\tan^{n-1} x}{n-1} - \int \tan^{n-2} x \, dx, n \neq 1.$
- (d) $\int \sec^n x \, dx = \frac{\sec^{n-2} x \tan x}{n-1} + \frac{n-2}{n-1} \int \sec^{n-2} x \, dx, n \neq 1.$

1.4 Trigonometric Substitutions

Proposition 1.3. The integral contains $a^2 - x^2$. Let $x = a \sin \theta$, $-\pi/2 \leq \theta \leq \pi/2$ for $|x| \leq a$. Then $a^2 - x^2 = a^2 - a^2 \sin^2 \theta = a^2(1 - \cos^2 \theta) = a^2 \cos^2 \theta$.

1.5 Partial Fractions

Procedure 1.3 (Partial Fractions with Simple Linear Factors). Suppose $f(x) = p(x)/q(x)$, where p and q are polynomials with no common factors and with the degree of p less than the degree of q . Assume that q is the product of simple linear factors. The partial fraction decomposition is obtained as follows.

- (a) *Factor the denominator q* in the form $(x - r_1)(x - r_2) \cdots (x - r_n)$, where r_1, \dots, r_n are real numbers.
- (b) *Partial fraction decomposition.* Form the partial fraction decomposition by writing

$$\frac{p(x)}{q(x)} = \frac{A_1}{(x - r_1)} + \frac{A_2}{(x - r_2)} + \cdots + \frac{A_n}{(x - r_n)}.$$

- (c) *Clear denominators.* Multiply both sides of the equation in Step (b) by $q(x) = (x - r_1)(x - r_2) \cdots (x - r_n)$, which produces conditions for A_1, \dots, A_n .
- (d) *Solve for coefficients.* Equate like powers of x in Step (c) to solve for the undetermined coefficients A_1, \dots, A_n .

Procedure 1.4 (Partial Fractions for Repeated Linear Factors). Suppose the repeated linear factor $(x - r)^m$ appears in the denominator of a proper rational function in reduced form. The partial fraction decomposition has a partial fraction for each power of $(x - r)$ up to and including the m th power; that is, the partial fraction decomposition contains the sum

$$\frac{A_1}{(x - r)} + \frac{A_2}{(x - r)^2} + \cdots + \frac{A_m}{(x - r)^m},$$

where A_1, \dots, A_m are constants to be determined.

Procedure 1.5 (Partial Fractions with Simple Irreducible Quadratic Factors). Suppose a simple irreducible factor $ax^2 + bx + c$ appears in the denominator of a proper rational function in reduced form. The partial fraction decomposition contains a term of the form

$$\frac{Ax + B}{ax^2 + bx + c},$$

where A and B are unknown coefficients to be determined.

Proposition 1.4. The quadratic polynomial $ax^2 + bx + c$ is irreducible if and only if its discriminant is negative, i.e.,

$$\Delta = b^2 - 4ac < 0.$$

Proposition 1.5 (Partial Fraction Decomposition). Let $f(x) = p(x)/q(x)$ be a proper rational function in reduced form. Assume the denominator q has been factored completely over the real numbers and m is a positive integer.

- (a) *Simple linear factor.* A factor $x - r$ in the denominator requires the partial fraction $\frac{A}{x - r}$.
- (b) *Repeated linear factor.* A factor $(x - r)^m$ with $m > 1$ in the denominator requires the partial fractions

$$\frac{A_1}{(x - r)} + \frac{A_2}{(x - r)^2} + \frac{A_3}{(x - r)^3} + \cdots + \frac{A_m}{(x - r)^m}.$$

- (c) *Simple irreducible quadratic factor.* An irreducible factor $ax^2 + bx + c$ in the denominator requires the partial fraction

$$\frac{Ax + B}{ax^2 + bx + c}.$$

- (d) *Repeated irreducible quadratic factor.* An irreducible factor $(ax^2 + bx + c)^m$ with $m > 1$ in the denominator requires the partial fractions

$$\frac{A_1x + B_1}{ax^2 + bx + c} + \frac{A_2x + B_2}{(ax^2 + bx + c)^2} + \cdots + \frac{A_mx + B_m}{(ax^2 + bx + c)^m}.$$

1.6 Numerical Integration

Definition 1.1 (Absolute and Relative Error). Suppose c is a computed numerical solution to a problem having an exact solution x . There are two common measures of the error in c as an approximation to x :

$$\text{absolute error} = |c - x|$$

and

$$\text{relative error} = \frac{c - x}{x}, (\text{if } x \neq 0).$$

Definition 1.2. Suppose f is defined and integrable on $[a, b]$. The *Midpoint Rule approximation* to $\int_a^b f(x) dx$ using n equally spaced subintervals on $[a, b]$ is

$$M(n) = f(m_1)\Delta x + f(m_2)\Delta x + \cdots + f(m_n)\Delta x = \sum_{k=1}^n f\left(\frac{x_{k-1} + x_k}{2}\right) \Delta x,$$

where $\Delta x = (b - a)/n$, $x_0 = a$, $x_k = a + k\Delta x$, and $m_k = (x_{k-1} + x_k)/2 = a + (k - 1/2)\Delta x$ is the midpoint of $[x_{k-1}, x_k]$, for $k = 1, \dots, n$.

Definition 1.3 (Trapezoid Rule). Suppose f is defined and integrable on $[a, b]$. The *Trapezoid Rule approximation* to $\int_a^b f(x) dx$ using n equally spaced subintervals on $[a, b]$ is

$$T(n) = \left[\frac{1}{2}f(x_0) + \sum_{k=1}^{n-1} f(x_k) + \frac{1}{2}f(x_n) \right] \Delta x.$$

where $\Delta x = (b - a)/n$ and $x_k = a + k\Delta x$, for $k = 0, 1, 2, \dots, n$.

Definition 1.4 (Simpson's Rule). Suppose f is defined and integrable on $[a, b]$ and $n \geq 2$ is an even integer. The *Simpson's Rule approximation* to $\int_a^b f(x) dx$ using n equally spaced subintervals on $[a, b]$ is

$$\begin{aligned} S(n) &= [f(x_0) + 4f(x_1) + 2f(x_2) + 4f(x_3) + \cdots + 4f(x_{n-1}) + f(x_n)] \frac{\Delta x}{3} \\ &= \sum_{k=0}^{n/2-1} [f(x_{2k}) + 4f(x_{2k+1}) + f(x_{2k+2})] \frac{\Delta x}{3}. \end{aligned}$$

where n is an even integer, $\Delta x = (b - a)/n$, and $x_k = a + k\Delta x$, for $k = 0, 1, \dots, n$.

1.7 Improper Integrals

Definition 1.5 (Improper Integrals over Infinite Intervals).

(a) If f is continuous on $[a, \infty)$, then

$$\int_a^\infty f(x) dx = \lim_{b \rightarrow \infty} \int_a^b f(x) dx.$$

- (b) If f is continuous on $(-\infty, b]$, then

$$\int_{-\infty}^b f(x) dx = \lim_{a \rightarrow -\infty} \int_a^b f(x) dx.$$

- (c) If f is continuous on $(-\infty, \infty)$, then

$$\int_{-\infty}^{\infty} f(x) dx = \lim_{a \rightarrow -\infty} \int_a^c f(x) dx + \lim_{b \rightarrow \infty} \int_c^b f(x) dx,$$

where c is any real number.

If the limits in the above cases exist, then the improper integrals *converge*; otherwise, they *diverge*.

Definition 1.6 (Improper Integrals with an Unbounded Integrand).

- (a) Suppose f is continuous on $(a, b]$ with $\lim_{x \rightarrow a^+} f(x) = \pm\infty$. Then

$$\int_a^b f(x) dx = \lim_{c \rightarrow a^+} \int_c^b f(x) dx.$$

- (b) Suppose f is continuous on $[a, b)$ with $\lim_{x \rightarrow b^-} f(x) = \pm\infty$. Then

$$\int_a^b f(x) dx = \lim_{c \rightarrow b^-} \int_a^c f(x) dx.$$

- (c) Suppose f is continuous on $[a, b]$ except at the interior point p where f is unbounded. Then

$$\int_a^b f(x) dx = \lim_{c \rightarrow p^-} \int_a^c f(x) dx + \lim_{d \rightarrow p^+} \int_d^b f(x) dx.$$

If the limits in above cases exist, then the improper integrals *converge*; otherwise, they *diverge*.

1.8 Introduction to Differential Equations

Definition 1.7.

- (a) The *order* of a differential equation is the highest order appearing on a derivative in the equation. For example, the equations $y' + 4y = \cos x$ and $y' = 0.1y(100 - y)$ are first order, and $y'' + 16y = 0$ is second order.
- (b) *Linear* differential equations (first- and second-order) have the form

$$y'(x) + p(x)y(x) = f(x) \text{ and } y''(x) + p(x)y'(x) + q(x)y(x) = f(x),$$

where p , q , and f are given functions that depend only on the independent variable x .

- (c) A differential equation is often accompanied by *initial conditions* that specify the values of y , and possibly its derivatives, at a particular point. In general, an n th-order equation requires n initial conditions.
- (d) A differential equation, together with the appropriate number of initial conditions, is called an *initial value problem*. A typical first-order initial value problem has the form

$$\begin{array}{ll} y'(t) = F(t, y) & \text{Differential equation} \\ y(0) = A & \text{Initial condition} \end{array}$$

where A is given and F is a given expression that involves t and/or y ,

Proposition 1.6 (Solution of a First-Order Linear Differential Equation). The general solution of the first-order equation $y'(t) = ky + b$, where k and b are specified real numbers, is $y = Ce^{kt} - b/k$, where C is an arbitrary constant. Given an initial condition, the value of C may be determined.

Definition 1.8 (Separable First-Order Differential Equations). If the first-order differential equation can be written in the form $g(y)y'(t) = h(t)$, in which the terms that involve y appear on one side of the equation *separated* from the terms that involve t , is said to be *separable*. We can solve the equation by integrating both sides of the equation with respect to t :

$$\int g(y)y'(t) dt = \int h(t) dt \implies \int g(y) dy = \int h(t) dt.$$

2 Sequences and Infinite Series

2.1 Sequences

Definition 2.1 (Sequence). A *sequence* $\{a_n\}$ is an ordered list of numbers of the form

$$\{a_1, a_2, a_3, \dots, a_n, \dots\}.$$

A sequence may be generated by a *recurrence relation* of the form $a_{n+1} = f(a_n)$, for $n = 1, 2, 3, \dots$, where a_1 is given. A sequence may also be defined with an *explicit formula* of the form $a_n = f(n)$, for $n = 1, 2, 3, \dots$.

Definition 2.2 (Limit of a Sequence). If the terms of a sequence $\{a_n\}$ approach a unique number L as n increases – that is, if a_n can be made arbitrarily close to L by taking n sufficiently large – then we say $\lim_{n \rightarrow \infty} a_n = L$ exists, and the sequence *converges* to L . If the terms of the sequence do not approach a single number as n increases, the sequence has no limit, and the sequence *diverges*.

Theorem 2.1 (Limits of Sequences from Limits of Functions). Suppose f is a function such that $f(n) = a_n$ for all positive integers n . If $\lim_{x \rightarrow \infty} f(x) = L$, then the limit of the sequence $\{a_n\}$ is also L .

Theorem 2.2 (Limit Laws for Sequences). Assume that the sequences $\{a_n\}$ and $\{b_n\}$ have limits A and B , respectively. Then

- (a) $\lim_{n \rightarrow \infty} (a_n \pm b_n) = A \pm B$.
- (b) $\lim_{n \rightarrow \infty} ca_n = cA$, where c is a real number.
- (c) $\lim_{n \rightarrow \infty} a_nb_n = AB$.
- (d) $\lim_{n \rightarrow \infty} \frac{a_n}{b_n} = \frac{A}{B}$ provided $B \neq 0$.

Definition 2.3 (Terminology for Sequences).

- (a) $\{a_n\}$ is *increasing* if $a_{n+1} > a_n$; for example, $\{0, 1, 2, 3, \dots\}$.
- (b) $\{a_n\}$ is *nondecreasing* if $a_{n+1} \geq a_n$; for example, $\{0, 1, 1, 1, 2, 2, 3, \dots\}$.
- (c) $\{a_n\}$ is *decreasing* if $a_{n+1} < a_n$; for example, $\{2, 1, 0, -2, \dots\}$.
- (d) $\{a_n\}$ is *nonincreasing* if $a_{n+1} \leq a_n$; for example, $\{2, 1, 1, 0, -2, -2, -3, \dots\}$.
- (e) $\{a_n\}$ is *monotonic* if it is either nonincreasing or nondecreasing (it moves in one direction).
- (f) $\{a_n\}$ is *bounded* if there is number M such that $|a_n| \leq M$, for all relevant values of n .

Theorem 2.3 (Squeeze Theorem for Sequences). Let $\{a_n\}$, $\{b_n\}$, and $\{c_n\}$ be sequences with $a_n \leq b_n \leq c_n$ for all integers n greater than some index N . If $\lim_{n \rightarrow \infty} a_n = \lim_{n \rightarrow \infty} c_n = L$, then $\lim_{n \rightarrow \infty} b_n = L$.

Theorem 2.4 (Bounded Monotonic Sequences). A bounded monotonic sequence converges.

Theorem 2.5 (Growth Rates of Sequences). The following sequences are ordered according to increasing growth rates as $n \rightarrow \infty$; that is, if $\{a_n\}$ appears before $\{b_n\}$ in the list, then $\lim_{n \rightarrow \infty} \frac{a_n}{b_n} = 0$ and $\lim_{n \rightarrow \infty} \frac{b_n}{a_n} = \infty$:

$$\{\ln^q n\} \ll \{n^p\} \ll \{n^p \ln^r n\} \ll \{n^{p+s}\} \ll \{b^n\} \ll \{n!\} \ll \{n^n\}.$$

The ordering applies for positive real numbers p, q, r, s and $b > 1$.

2.2 Limits of Functions

Theorem 2.6 (Limits of Linear Functions). Let a, b , and m be real numbers. For linear functions $f(x) = mx + b$,

$$\lim_{x \rightarrow a} f(x) = f(a) = ma + b.$$

Theorem 2.7 (Limit Laws). Assume $\lim_{x \rightarrow a} f(x)$ and $\lim_{x \rightarrow a} g(x)$ exist. The following properties hold, where c is a real number, and $m > 0$ and $n > 0$ are integers.

- (a) *Sum*: $\lim_{x \rightarrow a} [f(x) + g(x)] = \lim_{x \rightarrow a} f(x) + \lim_{x \rightarrow a} g(x)$.
- (b) *Difference*: $\lim_{x \rightarrow a} [f(x) - g(x)] = \lim_{x \rightarrow a} f(x) - \lim_{x \rightarrow a} g(x)$.
- (c) *Constant multiple*: $\lim_{x \rightarrow a} cf(x) = c \lim_{x \rightarrow a} f(x)$.
- (d) *Product*: $\lim_{x \rightarrow a} [f(x)g(x)] = \left[\lim_{x \rightarrow a} f(x) \right] \left[\lim_{x \rightarrow a} g(x) \right]$.
- (e) *Quotient*: $\lim_{x \rightarrow a} \left[\frac{f(x)}{g(x)} \right] = \frac{\lim_{x \rightarrow a} f(x)}{\lim_{x \rightarrow a} g(x)}$, provided $\lim_{x \rightarrow a} g(x) \neq 0$.
- (f) *Power*: $\lim_{x \rightarrow a} [f(x)]^n = \left[\lim_{x \rightarrow a} f(x) \right]^n$.

Theorem 2.8 (Limits of Polynomial and Rational Functions). Assume p and q are polynomials and a is a constant.

- (a) Polynomial functions: $\lim_{x \rightarrow a} p(x) = p(a)$.
- (b) Rational functions: $\lim_{x \rightarrow a} \frac{p(x)}{q(x)} = \frac{p(a)}{q(a)}$, provided $q(a) \neq 0$.

Theorem 2.9 (The Squeeze Theorem). Assume the function f, g , and h satisfy $f(x) \leq g(x) \leq h(x)$ for all values of x near a , except possibly at a . If $\lim_{x \rightarrow a} f(x) = \lim_{x \rightarrow a} h(x) = L$, then $\lim_{x \rightarrow a} g(x) = L$.

Theorem 2.10 (Limits at Infinity of Powers and Polynomials). Let n be a positive integer and let p be the polynomial $p(x) = a_n x^n + a_{n-1} x^{n-1} + \cdots + a_2 x^2 + a_1 x + a_0$, where $a_n \neq 0$.

- (a) $\lim_{x \rightarrow \pm\infty} x^n = \infty$ when n is even.
- (b) $\lim_{x \rightarrow \infty} x^n = \infty$ and $\lim_{x \rightarrow -\infty} x^n = -\infty$ when n is odd.

- (c) $\lim_{x \rightarrow \pm\infty} \frac{1}{x^n} = \lim_{x \rightarrow \pm\infty} x^{-n} = 0$.
- (d) $\lim_{x \rightarrow \pm\infty} p(x) = \lim_{x \rightarrow \pm\infty} a_n x^n = \pm\infty$, depending on the degree of the polynomial and the sign of the leading coefficient a_n .

Theorem 2.11 (End Behavior of e^x , e^{-x} , and $\ln x$). The end behavior for e^x and e^{-x} on $(-\infty, \infty)$ and $\ln x$ on $(0, \infty)$ is given by the following limits (see Figure 1):

$$\begin{array}{ll} \lim_{x \rightarrow \infty} e^x = \infty & \lim_{x \rightarrow -\infty} e^x = 0 \\ \lim_{x \rightarrow \infty} e^{-x} = 0 & \lim_{x \rightarrow -\infty} e^{-x} = \infty \\ \lim_{x \rightarrow 0^+} \ln x = -\infty & \lim_{x \rightarrow \infty} \ln x = \infty. \end{array}$$

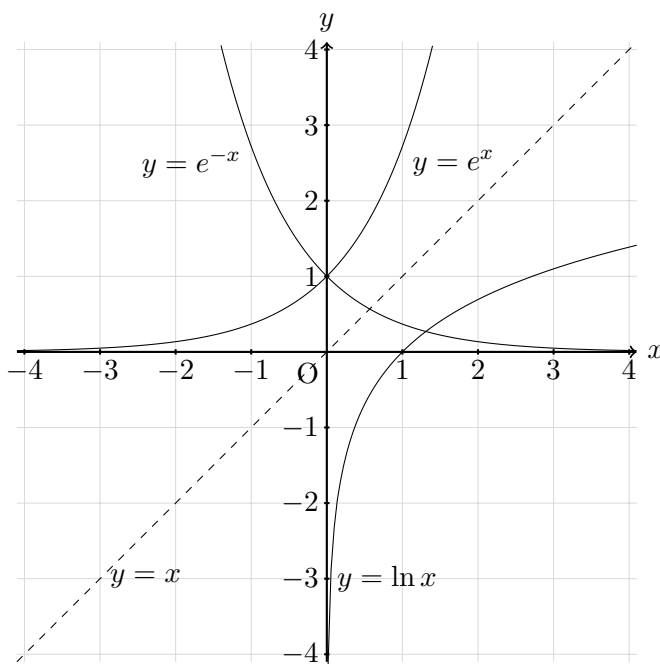


Figure 1: Graphs of e^x , e^{-x} , $\ln x$: $y = e^{-x}$ and $y = e^x$ are symmetric about y -axis, and $y = e^x$ and $y = \ln x$ are symmetric about $y = x$.

Theorem 2.12 (L'Hôpital's Rule). Suppose f and g are differentiable on an open interval I containing a with $g'(x) \neq 0$ on I when $x \neq a$.

- (a) If $\lim_{x \rightarrow a} f(x) = \lim_{x \rightarrow a} g(x) = 0$, then

$$\lim_{x \rightarrow a} \frac{f(x)}{g(x)} = \lim_{x \rightarrow a} \frac{f'(x)}{g'(x)},$$

provided the limit on the right exists (or is $\pm\infty$). The rule also applies if $x \rightarrow a$ is replaced with $x \rightarrow \pm\infty$, $x \rightarrow a^+$, $x \rightarrow a^-$.

(b) If $\lim_{x \rightarrow a} f(x) = \pm\infty$ and $\lim_{x \rightarrow a} g(x) = \pm\infty$, then

$$\lim_{x \rightarrow a} \frac{f(x)}{g(x)} = \lim_{x \rightarrow a} \frac{f'(x)}{g'(x)},$$

provided the limit on the right exists (or is $\pm\infty$). The rule also applies if $x \rightarrow a$ is replaced with $x \rightarrow \pm\infty$, $x \rightarrow a^+$, $x \rightarrow a^-$.

2.3 Infinite Series

Definition 2.4 (Infinite series). Given a sequence $\{a_1, a_2, a_3, \dots\}$, the sum of its terms

$$a_1 + a_2 + a_3 + \dots = \sum_{k=1}^{\infty} a_k$$

is called an *infinite series*. The *sequence of partial sums* $\{S_n\}$ associated with this series has the terms

$$S_1 = a_1$$

$$S_2 = a_1 + a_2$$

$$S_3 = a_1 + a_2 + a_3$$

$$\vdots$$

$$S_n = a_1 + a_2 + a_3 + \dots + a_n = \sum_{k=1}^n a_k, \text{ for } n = 1, 2, 3, \dots$$

If the sequence of partial sums $\{S_n\}$ has a limit L , the infinite series *converges* to that limit, and we write

$$\sum_{k=1}^{\infty} a_k = \lim_{n \rightarrow \infty} \sum_{k=1}^n a_k = \lim_{n \rightarrow \infty} S_n = L.$$

If the sequence of partial sums diverges, the infinite series also *diverges*.

2.4 Geometric Sequences and Geometric Series

Definition 2.5 (Geometric Sequences). A sequence has the form $\{r^n\}$ or $\{ar^n\}$, where the ratio r , a are real numbers, is called a geometric sequence.

Theorem 2.13 (Geometric Sequences). Let r be a real number. Then

$$\lim_{n \rightarrow \infty} r^n = \begin{cases} 0 & \text{if } |r| < 1, \\ 1 & \text{if } r = 1, \\ \text{does not exist} & \text{if } r \leq -1 \text{ or } r > 1. \end{cases}$$

If $r > 0$, then $\{r^n\}$ is a monotonic sequence. If $r < 0$, then $\{r^n\}$ oscillates.

Theorem 2.14 (Geometric Series). Let $a \neq 0$ and r be real numbers. If $|r| < 1$, then $\sum_{k=0}^{\infty} ar^k =$

$\frac{a}{1-r}$. If $|r| \geq 1$, then the series diverges. More generally,

$$\sum_{k=m}^{\infty} ar^k = \frac{ar^m}{1-r}.$$

3 Algebra

3.1 Exponents and Radicals

- (a) $\frac{1}{x^a} = x^{-a}$.
- (b) $\sqrt[n]{x} = x^{1/n}$.
- (c) $x^{a+b} = x^a x^b$.
- (d) $x^{a-b} = \frac{x^a}{x^b}$.
- (e) $x^{ab} = (x^a)^b$.
- (f) $x^{m/n} = \sqrt[n]{x^m} = (\sqrt[n]{x})^m$.
- (g) $(xy)^a = x^a y^a$.
- (h) $\left(\frac{x}{y}\right)^a = \frac{x^a}{y^a}$.

3.2 Logarithm

- (a) $y = a^x \implies x = \log_a y$.
- (b) $\log_e x = \ln x$.
- (c) $\log_b(xy) = \log_b x + \log_b y$.
- (d) $\log_b \frac{x}{y} = \log_b x - \log_b y$.
- (e) $\log_b(x^p) = p \log_b x$.
- (f) $\log_b(x^{1/p}) = \frac{1}{p} \log_b x$.
- (g) $\log_b x = \frac{\log_k x}{\log_k b}$.

3.3 Factoring Formulas

- (a) $a^2 - b^2 = (a - b)(a + b)$.
- (b) $a^3 - b^3 = (a - b)(a^2 + ab + b^2)$.
- (c) $a^n - b^n = (a - b)(a^{n-1} + a^{n-2}b + a^{n-3}b^2 + \cdots + ab^{n-2} + b^{n-1})$.

3.4 Binomials

- (a) $(a \pm b)^2 = a^2 \pm 2ab + b^2$.
- (b) $(a \pm b)^3 = a^3 \pm 3a^2b + 3ab^2 \pm b^3$.

3.5 Completing the Square

- (a) $(x \pm p)^2 = x^2 \pm 2px + p^2$.
- (b)

$$\begin{aligned}
 x^2 \pm bx + c &= x^2 \pm 2\frac{b}{2}x + c \\
 &= x^2 \pm 2\frac{b}{2}x + \left(\frac{b}{2}\right)^2 + c - \left(\frac{b}{2}\right)^2 \\
 &= \left(x \pm \frac{b}{2}\right)^2 + c - \frac{b^2}{4}.
 \end{aligned}$$

(c)

$$\begin{aligned} ax^2 \pm bx + c &= a \left(x^2 \pm \frac{b}{a}x \right) + c \\ &= a \left(x^2 \pm 2\frac{b}{2a}x \right) + c \\ &= a \left[x^2 \pm 2\frac{b}{2a}x + \left(\frac{b}{2a} \right)^2 \right] + c - a \left(\frac{b}{2a} \right)^2 \\ &= a \left(x \pm \frac{b}{2a} \right)^2 + c - \frac{b^2}{4a} \\ &= (\sqrt{a})^2 \left(x \pm \frac{b}{2a} \right)^2 + c - \frac{b^2}{4a} \\ &= \left(\sqrt{a}x \pm \frac{\sqrt{ab}}{2a} \right)^2 + c - \frac{b^2}{4a} \\ &= \left(\sqrt{a}x \pm \frac{b}{2\sqrt{a}} \right)^2 + c - \frac{b^2}{4a}. \end{aligned}$$

3.6 Quadratic Formula

The solutions of $ax^2 + bx + c = 0$ are

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}.$$