MATH 2205 - Calculus II Lecture Notes 14

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1 Integration Techniques

1.1 Review of Improper Integrals

Definition 1.1 (Improper Integrals over Infinite Intervals).

(a) If f is continuous on $[a, \infty)$, then

$$\int_{a}^{\infty} f(x) \, dx = \lim_{b \to \infty} \int_{a}^{b} f(x) \, dx.$$

(b) If f is continuous on $(-\infty, b]$, then

$$\int_{-\infty}^{b} f(x) \, dx = \lim_{a \to -\infty} \int_{a}^{b} f(x) \, dx.$$

(c) If f is continuous on $(-\infty, \infty)$, then

$$\int_{-\infty}^{\infty} f(x) \, dx = \lim_{a \to -\infty} \int_{a}^{c} f(x) \, dx + \lim_{b \to \infty} \int_{c}^{b} f(x) \, dx,$$

where c is any real number.

If the limits in the above cases exist, then the improper integrals *converge*; otherwise, they *diverge*.

Definition 1.2 (Improper Integrals with an Unbounded Integrand).

(a) Suppose f is continuous on (a, b] with $\lim_{x\to a^+} f(x) = \pm \infty$. Then

$$\int_{a}^{b} f(x) dx = \lim_{c \to a^{+}} \int_{c}^{b} f(x) dx.$$

(b) Suppose f is continuous on [a, b) with $\lim_{x\to b^-} f(x) = \pm \infty$. Then

$$\int_{a}^{b} f(x) \, dx = \lim_{c \to b^{-}} f(x) \, dx.$$

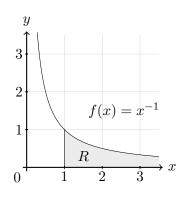
(c) Suppose f is continuous on [a, b] except at the interior point p where f is unbounded. Then

$$\int_{a}^{b} f(x) \, dx = \lim_{c \to p^{-}} \int_{a}^{c} f(x) \, dx + \lim_{d \to p^{+}} \int_{d}^{b} f(x) \, dx$$

If the limits in above cases exist, then the improper integrals *converge*; otherwise, they *diverge*.

Example 1.1 (Solids of revolution). Let R be the region bounded by the graph of $y = x^{-1}$ and the x-axis, for $x \ge 1$.

(a) What is the volume of the solid generated when R is revolved about the x-axis?



(b) What is the volume of the solid generated when R is revolved about the y-axis?

SOLUTION.

(a) Disk method.

$$V = \int_{a}^{b} \pi f(x)^{2} dx$$

$$= \int_{1}^{\infty} \pi (x^{-1})^{2} dx$$

$$= \pi \int_{1}^{\infty} x^{-2} dx$$

$$= \pi \lim_{b \to \infty} \int_{1}^{b} x^{-2} dx$$

$$= \pi \lim_{b \to \infty} (-x^{-1}) \Big|_{1}^{b}$$

$$= -\pi \lim_{b \to \infty} x^{-1} \Big|_{1}^{b}$$

$$= -\pi \lim_{b \to \infty} (b^{-1} - 1)$$

$$= -\pi (-1)$$

$$= \pi.$$

The volume of the solid when R is revolved about the x-axis is π .

(b) Shell method.

$$V = \int_{a}^{b} 2\pi x f(x) dx$$

=
$$\int_{1}^{\infty} 2\pi x x^{-1} dx$$

=
$$2\pi \int_{1}^{\infty} 1 dx$$

=
$$2\pi \lim_{b \to \infty} \int_{1}^{b} 1 dx$$

=
$$2\pi \lim_{b \to \infty} x \Big|_{1}^{b}$$

=
$$2\pi \lim_{b \to \infty} (b-1)$$

=
$$\infty.$$

In this case, the volume of the solid when R is revolved about the y-axis diverges.

Review for Computing Limits 1.2

Theorem 1.1 (Limits of Linear Functions). Let a, b, and m be real numbers. For linear functions f(x) = mx + b,

$$\lim_{x \to a} f(x) = f(a) = ma + b.$$

Theorem 1.2 (Limit Laws). Assume $\lim_{x\to a} f(x)$ and $\lim_{x\to a} g(x)$ exist. The following properties hold, where c is a real number, and m > 0 and n > 0 are integers.

- (a) Sum: $\lim_{x \to a} [f(x) + g(x)] = \lim_{x \to a} f(x) + \lim_{x \to a} g(x).$ (b) Difference: $\lim_{x \to a} [f(x) g(x)] = \lim_{x \to a} f(x) \lim_{x \to a} g(x).$ (c) Constant multiple: $\lim_{x \to a} cf(x) = c \lim_{x \to a} f(x).$ (d) Product: $\lim_{x \to a} [f(x)g(x)] = \left[\lim_{x \to a} f(x)\right] \left[\lim_{x \to a} g(x)\right].$ (e) Quotient: $\lim_{x \to a} \left[\frac{f(x)}{g(x)}\right] = \frac{\lim_{x \to a} f(x)}{\lim_{x \to a} g(x)}, \text{ provided } \lim_{x \to a} g(x) \neq 0.$

(f) Power:
$$\lim_{x \to a} [f(x)]^n = \left[\lim_{x \to a} f(x)\right]^n$$

(g) Fractional power: $\lim_{x \to a} [f(x)]^{n/m} = \left[\lim_{x \to a} f(x)\right]^{n/m}$, provided $f(x) \ge 0$, for x near a, if m is even and n/m is reduced to lowest terms.

Theorem 1.3 (Limits of Polynomial and Rational Functions). Assume p and q are polynomials and a is a constant.

- (a) Polynomial functions: $\lim_{x\to a} p(x) = p(a)$.
- (b) Rational functions: $\lim_{x \to a} \frac{p(x)}{q(x)} = \frac{p(a)}{q(a)}$, provided $q(a) \neq 0$.

Theorem 1.4 (The Squeeze Theorem). Assume the function f, g, and h satisfy $f(x) \leq g(x) \leq h(x)$ for all values of x near a, except possibly at a. If $\lim_{x\to a} f(x) = \lim_{x\to a} h(x) = L$, then $\lim_{x\to a} g(x) = L$.

Theorem 1.5 (Limits at Infinity of Powers and Polynomials). Let *n* be a positive integer and let *p* be the polynomial $p(x) = a_n x^n + a_{n-1} x^{n-1} + \cdots + a_2 x^2 + a_1 x + a_0$, where $a_n \neq 0$.

- (a) $\lim_{x\to\pm\infty} x^n = \infty$ when n is even.
- (b) $\lim_{x\to\infty} x^n = \infty$ and $\lim_{x\to-\infty} x^n = -\infty$ when n is odd.
- (c) $\lim_{x \to \pm \infty} \frac{1}{x^n} = \lim_{x \to \pm \infty} x^{-n} = 0.$
- (d) $\lim_{x\to\pm\infty} p(x) = \lim_{x\to\pm\infty} a_n x^n = \pm\infty$, depending on the degree of the polynomial and the sign of the leading coefficient a_n .

Example 1.2. Let
$$p(x) = \sum_{k=0}^{n} a_k x^k = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$$
 and $q(x) = \sum_{k=0}^{m} b_k x^k = b_m x^m + b_{m-1} x^{m-1} + \dots + b_1 x + b_0$. What is $\lim_{x \to \infty} \frac{p(x)}{q(x)}$?

SOLUTION. It is known that $\lim_{x\to\infty} x^n = \begin{cases} \infty & \text{if } n > 0\\ 0 & \text{if } n < 0 \end{cases}$.

$$\begin{split} \lim_{x \to \infty} \frac{p(x)}{q(x)} &= \lim_{x \to \infty} \frac{a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0}{b_m x^m + b_{m-1} x^{m-1} + \dots + b_1 x + b_0} \\ &= \lim_{x \to \infty} \frac{a_n + a_{n-1} x^{-1} + \dots + a_1 x^{-n+1} + a_0 x^{-n}}{b_m x^{m-n} + b_{m-1} x^{m-n-1} + \dots + b_1 x^{1-n} + b_0 x^{-n}} \\ &= \frac{\lim_{x \to \infty} a_n + a_{n-1} x^{-1} + \dots + a_1 x^{-n+1} + a_0 x^{-n}}{\lim_{x \to \infty} b_m x^{m-n} + b_{m-1} x^{m-n-1} + \dots + b_1 x^{1-n} + b_0 x^{-n}} \\ &= \frac{a_n}{\lim_{x \to \infty} b_m x^{m-n} + b_{m-1} x^{m-n-1} + \dots + b_1 x^{1-n} + b_0 x^{-n}} \\ &= \begin{cases} a_n/b_m & \text{if } m = n, \\ \infty & \text{if } m < n, \\ 0 & \text{if } m > n. \end{cases} \end{split}$$

Theorem 1.6 (End Behavior of e^x , e^{-x} , and $\ln x$). The end behavior for e^x and e^{-x} on $(-\infty, \infty)$ and $\ln x$ on $(0, \infty)$ is given by the following limits (see Figure 1):

$$\lim_{\substack{x \to \infty}} e^x = \infty \qquad \qquad \lim_{\substack{x \to -\infty}} e^x = 0$$
$$\lim_{\substack{x \to \infty}} e^{-x} = 0 \qquad \qquad \lim_{\substack{x \to -\infty}} e^{-x} = \infty$$
$$\lim_{\substack{x \to 0^+}} \ln x = -\infty \qquad \qquad \lim_{\substack{x \to \infty}} \ln x = \infty.$$

Theorem 1.7 (L'Hôpital's Rule). Suppose f and g are differentiable on an open interval I containing a with $g'(x) \neq 0$ on I when $x \neq a$.

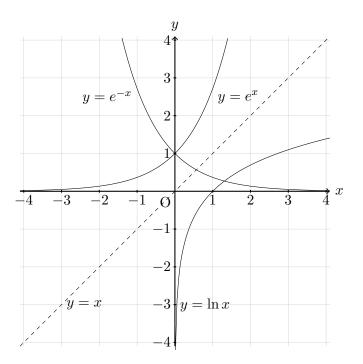


Figure 1: Graphs of e^x , e^{-x} , $\ln x$: $y = e^{-x}$ and $y = e^x$ are symmetric about y-axis, and $y = e^x$ and $y = \ln x$ are symmetric about y = x.

(a) If $\lim_{x\to a} f(x) = \lim_{x\to a} g(x) = 0$, then

$$\lim_{x \to a} \frac{f(x)}{g(x)} = \lim_{x \to a} \frac{f'(x)}{g'(x)},$$

provided the limit on the right exists (or is $\pm \infty$). The rule also applies if $x \to a$ is repaced with $x \to \pm \infty$, $x \to a^+$, $x \to a^-$.

(b) If $\lim_{x\to a} f(x) = \pm \infty$ and $\lim_{x\to a} g(x) = \pm \infty$, then

$$\lim_{x \to a} \frac{f(x)}{g(x)} = \lim_{x \to a} \frac{f'(x)}{g'(x)},$$

provided the limit on the right exists (or is $\pm \infty$). The rule also applies if $x \to a$ is repaced with $x \to \pm \infty$, $x \to a^+$, $x \to a^-$.

1.3 Introduction to Differential Equations

Example 1.3 (Differential Equations). Examples of differential equations:

(a)
$$y''(x) + 16y = 0.$$

(b) $\frac{dy}{dx} + 4y = \cos x.$
(c) $y'(t) = 0.1y(100 - y).$

In each case, the goal is to find solution of the equation – that is, functions y that satisfy the equation.

Definition 1.3.

- (a) The order of a differential equation is the highest order appearing on a derivative in the equation. For example, the equations $y' + 4y = \cos x$ and y' = 0.1y(100 y) are first order, and y'' + 16y = 0 is second order.
- (b) Linear differential equations (first- and second-order) have the form

y'(x) + p(x)y(x) = f(x) and y''(x) + p(x)y'(x) + q(x)y(x) = f(x),

where p, q, and f are given functions that depend only on the independent variable x.

- (c) A differential equation is often accompanied by *initial conditions* that specify the values of y, and possibly its derivatives, at a particular point. In general, an *n*th-order equation requires n initial conditions.
- (d) A differntial equation, together with the appropriate number of initial conditions, is called an *initial value problem*. A typical first-order initial value problem has the form

y'(t) = F(t, y)	Differential equation
y(0) = A	Initial condition

where A is given and F is a given expression that involves t and/or y,

Example 1.4 (An initial value problem). Solve the initial value problem

$$y'(t) = 10e^{-t/2}, y(0) = 4$$

SOLUTION. Notice that the right side of the equation depends only on t. The solution is found by integrating both sides of the differential equation with respect to t:

$$\int y'(t) \, dt = \int 10e^{-t/2} dt \implies y = -20e^{-t/2} + C.$$

We have found the general solution, which involves one arbitrary constant. To determine its value, we use the initial condition by substituting t = 0 and y = 4 into the general solution:

$$y(0) = (-20e^{-t/2} + C) \bigg|_{t=0} = -20 + C = 4 \implies C = 24.$$

Therefore, the solution of the initial value problem is $y = -20e^{-t/2} + 24$.

Proposition 1.1 (Solution of a First-Order Linear Differential Equation). The general solution of the first-order equation y'(t) = ky + b, where k and b are specified real numbers, is $y = Ce^{kt} - b/k$, where C is an arbitrary constant. Given an initial condition, the value of C may be determined.

Proof. Given that y'(t) = ky + b, we begin by dividing both sides of the equation y'(t) = ky + b by ky + b, which gives

$$\frac{y'(t)}{ky+b} = 1.$$

Integrating both sides of this equation with respect to t,

$$\int \frac{y'(t)}{ky+b} dt = \int dt \iff \int \frac{1}{ky+b} dy = \int dt.$$

Using change of variable (u-substitution) we have

$$\frac{1}{k}\ln|ky+b| = t+D$$

Assume that $ky + b \ge 0$, solving for y gives

$$y = e^{kD+kt} - \frac{b}{k} = e^{kD}e^{kt} - \frac{b}{k} = Ce^{kt} - \frac{b}{k},$$

where $C = e^{kD}$ is a constant.